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## CASE OF A GENERATING FAMILY OR QUASI-PERIODIC SOLUTIONS

## IN THE THEORY OF SMALL PARAMETER

PMM Vol. 37, N²6, 1973, pp. 990-998<br>R.F.NAGAEV<br>(Leningrad)<br>(Received August 21, 1972)

We consider the problem of the existence and the stability in-the-small of periodic solutions of systems of ordinary differential equations with a small parameter $\mu$, which in the generating approximation ( $\mu=0$ ) admit of a family of quasi-periodic solutions (we are concerned only with the solutions belonging to the indicated family when $\mu=0$ ). The case to be investigated is in a specific sense a more general case of the unisolated generating solution in the small parameter theory and, therefore, includes everything previously treated by Malkin [1], Blekhman [2], and others. The main difficulty in the investigation is the presence of a multiple zero root in the characteristic determinant of the problem's generating system, to which both simple as well as quadratic elementary divisors [3] correspond. This fact predestines the presence of three groups of stability criteria for the solution being examined. The method for constructing these criteria, proposed here, assumes, in contrast to a previous one [1], the preliminary determination of not only the generating approximation but also the first one to the desired periodic solution. Particular aspects of the general "mixed" problem treated here were studied earlier in [4, 5].

1. Existence of a periodic solution. At present relatively general integrability tests and integration methods for systems of high-order nonlinear differential equations have been worked out only for autonomous canonical systems [6]. The successive use of these methods leads, in the case of a sign-definite Hamiltonian function, to the determination of a general quasi-periodic integral. The conjugate canonic variables of the problem are here expressed as $2 \pi$-periodic functions of the quantities

$$
\begin{equation*}
\psi_{s}=v_{s} t+\alpha_{s} \tag{1.1}
\end{equation*}
$$

and also of the mutually independent integration constants $h_{s}(s=1,2, \ldots)$. Naturally, the total number of quantities $\psi_{s}, h_{s}$ equals the order of the original system. If the quantities $\alpha_{s}$ are integration constants, also independent of each other and of $h_{s}$ (and we assume this is so in what follows), then the quantities $\psi_{s}$ acquire the nature of partial rapidly-rotating phases and, moreover, the partial frequencies $v_{s}$ depend, as does
the energy constant, only on the $h_{s}$ in the general case. Sometimes the constants $h_{s}$ take on the meaning of partial actions. In that case we usually speak of the pair $h_{s}$, $\psi_{s}$ as the canonic pair "action - angle".

A more common case can occur when the system under investigation can be separated into two subsystems by some means or other. One of them being canonical and integrable, the other, either linear and stationary relative to the proper variables or admitting of the construction of a particular periodic solution by Liapunov's method [1] or by some other local method. Here, naturally, the family of quasi-periodic solutions of the original system can be constructed by purely analytic means. Thus, the periodic solution, constructed by known analytic methods, of a high-order system is in practice always a part of some family of quasi-periodic solutions.

Keeping what has been said in mind, in the general case we assume that the system

$$
\begin{equation*}
x=X(x, \psi, \mu) \tag{1.2}
\end{equation*}
$$

where $x$ is a $k \times 1$ vector, the vector-valued function $X$ is analytic in $x$ and $\mu$ and $2 \pi$-periodic in the dimensionless argument $\psi=v t(v>0)$, admits of a family of quasi-periodic solution for $\mu=0$

$$
\begin{equation*}
x(t, 0)=\varphi\left(\psi, \psi_{1}, \ldots, \psi_{l}, h_{1}, \ldots, h_{n}\right) \tag{1.3}
\end{equation*}
$$

Here the rapidly rotating phases $\psi_{s}(s=1, \ldots, l)$ and the constants $h_{s}(s=1, \ldots$, $n$ ) have the previous meaning. Furthermore, $l+n \leqslant k$. For the sake of generality we assume that the first $m$ partial frequencies of family (1.3) essentially depend on the constants $h_{1}, \ldots, h_{n}$, while the $l-m$ succeeding ones identically equal $v$, i.e.

$$
\begin{array}{ll}
v_{s}=v_{s}\left(h_{1}, \ldots, h_{n}\right) & (s=1, \ldots, m)  \tag{1.4}\\
v_{s} \equiv v & (s=m+1, \ldots, l)
\end{array}
$$

We note also that the Fourier expansion of the vector-valued function $\varphi$ may, in general, not contain several (but not very many) first harmonics of the phases $\psi, \psi_{1}, \ldots, \psi_{l}$.

The membership of (1.3) in the subfamily of solutions $T$-periodic in $t(T=2 \pi / v)$ is characterized by the fulfillment of the relations

$$
\begin{equation*}
v_{s}\left(h_{1}, \ldots, h_{n}\right)=v \quad(s=1, \ldots, m) \tag{1.5}
\end{equation*}
$$

and, therefore, depends only on $l+n-m$ independent constants among which are the phase shifts $\alpha_{1}, \ldots, \alpha_{1}$. Therefore, the variational system

$$
\begin{equation*}
y^{\cdot}=\frac{\partial X}{\partial x} y \tag{1.6}
\end{equation*}
$$

which for $\mu=0\left(y=y_{0}\right)$ is not far from the above-mentioned periodic motions, admits, in accordance to a theorem of Poincare [1], of $l$ mutually independent $T$-periodic solutions $\partial \varphi / \partial \alpha_{i}(i=1, \ldots, l)$ and of $n$ linearly increasing

$$
\begin{equation*}
\frac{\partial^{\prime} \varphi}{\partial h_{s}}=\sum_{i=1}^{m} \frac{\partial \varphi}{\partial \alpha_{i}} \frac{\partial v_{i}}{\partial h_{s}} t+\frac{\partial \varphi}{\partial h_{s}} \quad(s=1, \ldots, n) \tag{1.7}
\end{equation*}
$$

The prime here denotes "total" partial differentiation.
The family (1.7) of $n$ mutually independent solutions of the linear system (1.6) can be replaced when $\mu=0$ by a family of $m$ linearly increasing and $n-m$ periodic solutions. Indeed, under condition (1.5) we assume that the determinant

$$
\left|\frac{\partial v_{i}}{\partial h_{s}}\right|_{i, s=1, \ldots, m}
$$

is nonzero. Then, the numbers $\chi_{s r}$ are completely uniquely determined from the relations

$$
\begin{equation*}
\sum_{s=1}^{m} \chi_{s r} \frac{\partial v_{i}}{\partial h_{s}}=\delta_{i r} \quad(i, r=1, \ldots, m) \tag{1.8}
\end{equation*}
$$

The quantities

$$
\begin{equation*}
\boldsymbol{\vartheta}_{r}=\sum_{s=1}^{m} \chi_{s r} \frac{\partial^{\prime} \varphi}{\partial h_{s}} \tag{1.9}
\end{equation*}
$$

are linear combinations of the first $m$ solutions in (1.7) and, therefore, also satisfy system (1.6) with $\mu=0$. On the other hand, if we substitute (1.7) into (1.9), then as a consequence of (1.8) we have, after replacing the index $r$ by $i$,

$$
\begin{equation*}
\boldsymbol{\vartheta}_{i}=\frac{\partial \varphi}{\partial \alpha_{i}} t+\sigma_{i} \quad(\quad(=1, \ldots, m) \tag{1.10}
\end{equation*}
$$

Here the periodic component $\sigma_{i}$ is determined from the formula

$$
\begin{equation*}
\sigma_{i}=\sum_{s=1}^{m} \chi_{s i} \frac{\partial \varphi}{\partial h_{s}} \tag{1.11}
\end{equation*}
$$

and, as a consequence of (1.6) and (1.10), satisfies the equation

$$
\begin{equation*}
\sigma_{i}^{\cdot}=\left(\frac{\partial X}{\partial x}\right) \sigma_{i}-\frac{\partial \varphi}{\partial \alpha_{i}} \quad(i=1, \ldots, m) \tag{1.12}
\end{equation*}
$$

In Eqs. (1.12) and below the parantheses denote that the corresponding quantity is computed for $x=\varphi$ and $\mu=0$.

We introduce the quantities

$$
\begin{equation*}
\vartheta_{s}=\frac{\partial^{\prime} \varphi}{\partial h_{s}}-\sum_{i, r=1}^{m} \chi_{i r} \frac{\partial^{\prime} \varphi}{\partial h_{i}} \frac{\partial v_{r}}{\partial h_{s}} \quad(s=m+1, \ldots, n) \tag{1,13}
\end{equation*}
$$

which obviously also satisfy system (1.6) with $\mu=0$. Since by virtue of (1.8) the linearly increasing terms vanish after the substitution of (1.7) into (1.13), the quantities $\boldsymbol{\vartheta}_{s}(s=m+1, \ldots, n)$ are periodic in $t$ and can be represented as

$$
\begin{equation*}
\vartheta_{s}=\frac{\partial \varphi}{\partial h_{s}}-\sum_{i, r=1}^{m} \chi_{i r} \frac{\partial \varphi}{\partial h_{i}} \frac{\partial v_{r}}{\partial h_{s}} \quad(s=m+1, \ldots, n) \tag{1.14}
\end{equation*}
$$

Together with (1.14) the following expressions, ensuing from (1.11), are also valid:

$$
\begin{equation*}
\vartheta_{s}=\frac{\partial \varphi}{\partial h_{s}}-\sum_{i=1}^{m} \frac{\partial v_{i}}{\partial h_{s}} \sigma_{i} \quad(s=m+1, \ldots, n) \tag{1.15}
\end{equation*}
$$

Thus, the system of variational equations of the generating system of the problem ( $\mu=$ 0 ) admits of $l+n-m$ mutually independent $T$-periodic solutions $\partial \varphi^{\circ} / \partial \alpha_{i}(i=$ $1, \ldots, l)$ and $\vartheta_{s}(s=m+1, \ldots, n)$. We assume that this system admits of no other independent $T$-periodic solutions. Then the conjugate system

$$
\begin{equation*}
z^{*}=-z(\partial X / \partial x) \tag{1.16}
\end{equation*}
$$

also admits of $l+n-m$ mutually independent $T$-periodic particular solutions which we subsequently denote by $z_{1}, \ldots, z_{l+n-m} \bullet$

In connection with the problem being considered, it has been shown in local small parametr theory [1] that for the analyticity in $\mu$ and the $T$-periodicity in $t$ of the solution $x\left(t, \alpha_{1}, \ldots, \alpha_{l}, h_{1}, \ldots, h_{n}, \mu\right)$ of system (1.2), which becomes (1.3) when $\mu=0$, it is sufficient that the transcendental system consisting of the $m$ equations in (1.5) and, in addition, of the $l+n-m$ equations

$$
\begin{equation*}
P_{s}\left(\alpha_{1}, \ldots, \alpha_{l}, h_{1}, \ldots, h_{n}\right) \equiv \int_{v}^{T} z_{s}\left(\frac{\partial X}{\partial \mu}\right)^{\prime} d t=0 \quad(s=1, \ldots, l+n-m) \tag{1.17}
\end{equation*}
$$

admit of simple solutions. These solutions, of course, uniquely determine the $T$-periodic generating approximation in the expansion

$$
x=\varphi+\mu x_{1}+\mu^{2} x_{2}+\mu^{3} \ldots
$$

On the other hand, the presence of such a solution guarantees the $T$-periodicity of the sequence of corrections $x_{1}, x_{2}, \ldots$ We note that the first approximation $x_{1}=(\partial x /$ $\partial \mu$ ) to the solution $x\left(t, \alpha_{1}, \ldots, \alpha_{l}, h_{1}, \ldots, h_{n}, \mu\right)$, not necessarily periodic, can be found from the system

$$
x_{1}^{\cdot}=\left(\frac{\partial X}{\partial x}\right) x_{1}+\left(\frac{\partial X}{\partial \mu}\right)
$$

2. Stability criteria of the first group. The analysis in Sect. 1 shows that the variational equations of the generating system admit of $m$ groups of solutions $\partial \varphi / \partial \alpha_{i}$, $\vartheta_{i}(i=1, \ldots, m)$, to which correspond zero characteristic indices with quadratic elementary divisors $[1,3]$. The roots of the characteristic determinant of system (1.6), corresponding to these solutions, are analytic in $\mu^{1 / 2}$ [7]. On the other hand, to the simple periodic solutions $\partial \varphi / \partial \alpha_{i}(i=m+1, \ldots, l), \vartheta_{s}(s=m+1, \ldots, n)$ there correspond zero characteristic indices with simple elementary divisors. The characteristic indices of system (1.6), reducing to them as $\mu \rightarrow 0$, are analytic in $\mu$.

We turn to the direct determination of the "critical" solutions of system (1.6). Introducing the substitution [1]

$$
\begin{equation*}
y=\eta \exp \lambda(\mu) t \tag{2.1}
\end{equation*}
$$

we seek the $T$-periodic solutions of the system

$$
\begin{equation*}
\eta^{\cdot}=\frac{\partial X}{\partial x} \eta-\lambda \eta \tag{2.2}
\end{equation*}
$$

We represent the $T$-periodic particular solutions, analytic in $\mu$, of (2.2) in the form

$$
\begin{equation*}
\eta=\eta_{0}+\mu \eta_{1}+\mu^{2} \ldots, \quad \lambda=\lambda_{1} \mu+\mu^{2} \ldots \tag{2.3}
\end{equation*}
$$

Obviously, the generating periodic approximation $\eta_{0}$, can be represented as a superposition of periodic solutions of the variational equations of the generating system, i.e.

$$
\begin{equation*}
\eta_{0}=\sum_{i=1}^{l} \frac{\partial \varphi}{\partial x_{i}} a_{i}+\sum_{s=m+1}^{n} \vartheta_{s} b_{s} \tag{2.4}
\end{equation*}
$$

where $a_{1}, \ldots, a_{l}, b_{m+1}, \ldots, b_{n}$ are constants. Differentiating (2.2) with respect to $\mu$ and then setting $\mu=0$, we obtain and equation for determining $\eta_{1}$

$$
\begin{equation*}
\eta_{1} \cdot\left(\frac{\partial X}{\partial x}\right) i_{1}-\uparrow\left[\left(\frac{\partial^{\prime}}{\partial \mu} \frac{\partial X}{\partial x}\right)-\lambda_{1} E_{h}\right]\left(\sum_{i=1}^{l} \frac{\partial \varphi}{\partial x_{i}} a_{i}+\sum_{s=m+1}^{n} \vartheta_{s} h_{s}\right) \tag{2.5}
\end{equation*}
$$

where $E_{k}$ is the $k \times k$ unit matrix. Since by virtue of (1.2)

$$
\begin{equation*}
\left[\frac{\partial^{\prime}}{\partial \mu} \frac{\partial X}{\partial x}\right] \frac{\partial x}{\partial \alpha_{i}} \equiv \frac{\partial^{2} x^{\prime}}{\partial \mu \partial \alpha_{i}}-\frac{\partial X}{\partial x} \frac{\partial^{2} x}{\partial \mu \partial x_{i}} \tag{2.6}
\end{equation*}
$$

with due regard to (1.13) system (2.5) can be reduced to the form

$$
\begin{align*}
\boldsymbol{\eta}_{1}^{\cdot}= & \left(\frac{\partial X}{\partial x}\right) \eta_{1}+\sum_{i=1}^{l}\left[\frac{\partial x_{1}}{\partial \alpha_{i}}-\left(\frac{\partial X}{\partial x}\right) \frac{\partial x_{1}}{\partial x_{i}}-\lambda_{1} \frac{\partial \varphi}{\partial x_{i}}\right] a_{i}+  \tag{2.7}\\
& \sum_{s=m+1}^{n}\left[\frac{\partial^{*} x_{1}}{\partial h_{s}}-\left(\frac{\partial X}{\partial x}\right) \frac{\partial^{*} x_{1}}{\partial h_{s}}-\lambda_{1} \vartheta_{s}\right] b_{s}
\end{align*}
$$

Here we have introduced the notation

$$
\begin{equation*}
\frac{\partial^{*}}{\partial h_{s}}=\frac{\partial}{\partial h_{s}}-\sum_{i, r=1}^{m} \chi_{i r} \frac{\partial v_{r}}{\partial h_{s}} \frac{\partial}{\partial h_{i}} \tag{2.8}
\end{equation*}
$$

We now carry out a partial orthogonalization and normalization of the periodic solutions of system (1.16) in accordance with the equalities

$$
\begin{equation*}
z_{r} \frac{\partial \varphi}{\partial \alpha_{i}}=\delta_{i r} \quad(i=m+1, \ldots, l) . \quad z_{r} \vartheta_{s}=\delta_{l-m+s, r} \quad(s=m+1, \ldots, n) \tag{2.9}
\end{equation*}
$$

Furthermore, since the quantities $\hat{v}_{i}(i=1, \ldots, m)$, defined by (1.10), satisfy the relations $z_{r}, v_{i} \equiv$ const and, consequently,

$$
\begin{equation*}
z_{r} \frac{\partial \varphi}{\partial \alpha_{i}} \equiv 0 \quad(i=1, \ldots, m) \tag{2.10}
\end{equation*}
$$

after some manipulations with due regard to (1.16) and (2.7), we obtain

$$
\frac{d}{d t} z_{r}\left(\eta_{1}-\sum_{i=1}^{l} \frac{\partial x_{1}}{\partial \alpha_{i}} a_{i}-\sum_{s=m+1}^{n} \frac{\partial^{*} x_{1}}{\partial h_{s}} b_{s}\right)=\left\{\begin{array}{c}
0(r=1, \ldots, m)  \tag{2.11}\\
-\lambda_{1} a_{r} \quad(r=m+1, \ldots, l) \\
-\lambda_{1} b_{r-l+m}(r=1+1, \ldots \\
\ldots, l+l-m)
\end{array}\right.
$$

We integrate these relations with respect to $t$ in the limits from zero to $T$. Then, since

$$
\begin{equation*}
\left.\left.z_{r} \frac{\partial x_{1}}{\partial x_{i}}\right|_{0} ^{T} \equiv \frac{\partial}{\partial x_{i}}\left(z_{r} \bar{x}_{1}\right)\right|_{0} ^{T},\left.\left.\quad z_{r} \frac{\partial x_{1}}{\partial h_{s}}\right|_{0} ^{T} \equiv \frac{\partial}{\partial h_{s}}\left(z_{r} x_{1}\right)\right|_{0} ^{T},\left.z_{r} x_{1}\right|_{0} ^{T} \equiv P_{r} \tag{2.12}
\end{equation*}
$$

it turns out that the fulfillment of the following linear equations:

$$
\sum_{i=1}^{l} \frac{\partial P_{r}}{\partial \alpha_{i}} \alpha_{i}+\sum_{s=m+1}^{n} \frac{\partial^{*} P_{r}}{\partial h_{s}} b_{s}= \begin{cases}0 & (r=1, \ldots, m)  \tag{2.13}\\ \lambda_{1} T a_{r} & (r=m+1, \ldots, l) \\ \lambda_{1} T b_{r-l+m} & (r=l+1, \ldots, l+n-m)\end{cases}
$$

is necessary and sufficient for the $T$-periodicity of the quantity $\eta_{1}$. Equating the determinant of this system to zero, we arrive at an equation of degree $l+n-2 m$ for determining the first approximations to the "simple" critical characteristic indices of the problem. The $l+n-2 m$ stability criteria following from this we call stability criteria of the first group.
3. Additional stability criteria. In contrast to (2.3) the "nonsimple" critical solutions of system (2.2) are represented as

$$
\begin{equation*}
\eta=\eta_{0}+\mu^{1 / 2} \eta_{1}+\mu \eta_{2}+\mu^{3 / 2} \ldots, \quad \lambda=\lambda_{1} \mu^{1_{2}}+\lambda_{2} \mu+\mu^{3} \tag{3.1}
\end{equation*}
$$

Here, as before, the periodic generating approximation can be written in form (2.4). However, by virtue of the fact that the components of the matrix $\partial X / \partial x$ are analytic in $\mu$, the system of equations for determining the first approximation $\eta_{1}$ has the form

$$
\begin{equation*}
\eta_{1}^{\cdot}=\left(\frac{\partial X}{\partial x}\right) \eta_{1}-\lambda_{1}\left(\sum_{i=1}^{l} \frac{\partial \varphi}{\partial \alpha_{i}} a_{i}+\sum_{s=m+1}^{n} \vartheta_{s} b_{s}\right) \tag{3.2}
\end{equation*}
$$

The general $T$-periodic solution of this system exists only if $a_{m+1}=\ldots=a_{l}=$ $b_{m+1}=\ldots=b_{n}=0$ and, by virtue of (1.12), can be written in the form

$$
\begin{equation*}
\eta_{1}=\lambda_{1} \sum_{i=1}^{m} \sigma_{i} a_{i}+\sum_{i=1}^{\prime} \frac{\partial \varphi}{\partial x_{i}} c_{i}+\sum_{s=m+1}^{n} \vartheta_{s} d_{s} \tag{3.3}
\end{equation*}
$$

where $c_{1}, \ldots, c_{l}, d_{m+1}, \ldots, d_{n}$ are the new constants of integration. Thus, $\eta_{1}$ depends now on $l+n$ constants. The periodic second approximation $\eta_{2}$ is determined from the system

$$
\begin{align*}
\eta_{2}^{*} & =\left(\frac{\partial X}{\partial x}\right) \eta_{2}+\sum_{i=1}^{m}\left\{\left[\left(\frac{\partial^{\prime}}{\partial \mu} \frac{\partial X}{\partial x}\right)-\lambda_{2} E_{k}\right] \frac{\partial \varphi}{\partial \alpha_{i}}-\lambda_{1}{ }^{2} \sigma_{i}\right\} a_{i}-  \tag{3.4}\\
& \lambda_{1}\left(\sum_{i=1}^{l} \frac{\partial \varphi}{\partial x_{i}} c_{i}+\sum_{s=m+1}^{n} \grave{\vartheta}_{s} d_{s}\right)
\end{align*}
$$

We now assume the fulfillment of the relations

$$
\begin{equation*}
z_{r} \sigma_{i}=\delta_{i r} \quad(i,-1, \ldots, m) \tag{3.5}
\end{equation*}
$$

which together with (2.9) completely determine the choice of the orthogonal and normalized solutions $z_{1}, \ldots, z_{1+n-m}$ of system (1.16). Then, proceeding as before, with due regard to (2.6) and (3.4), we obtain

$$
\frac{d}{d t} z_{r}\left(r_{2}-\sum_{i=1}^{m} \frac{\partial x_{i}}{\partial x_{i}} a_{i}\right)= \begin{cases}-\lambda_{1} a_{l_{r}} & (r=1, \ldots, m)  \tag{3.6}\\ -\lambda_{1} r_{r} & (r, m-1, \ldots, l) \\ -\lambda_{1} d_{r-l_{+1} / \prime} & (r=1-1, \ldots, l+n-m)\end{cases}
$$

Integrating these relations with respect to $t$ in the limits from 0 to $T$, with due regard to (2.11), we get that for the periodicity of $\eta_{2}$ it is necessary and sufficient to fulfill the following $l+n-m$ homogeneous linear equations in the unknowns $a_{1}, \ldots$, $a_{m}, c_{m+1}, \ldots, c_{l}, d_{m+1}, \ldots, d_{n}:$

$$
\sum_{i=1}^{m} \frac{\partial P_{r}}{\partial x_{i}} a_{i}= \begin{cases}\lambda_{1} \uparrow T a_{T} & (r-1, \ldots, m)  \tag{3.7}\\ \lambda_{1} T c_{r} & (r=m+1, \ldots, l) \\ \lambda_{1} T d_{r-l+m} & (r=l+\mathbf{1}, \ldots, l+n-m)\end{cases}
$$

We note that as a consequence of (1.12) the values of the constants $c_{1}, \ldots, c_{m}$ and $\lambda_{2}$ prove to have no influence on the $T$-periodicity of $\eta_{2}$ The expression for $\eta_{2}$ obtaincd as a result of integrating (3.4) can be written in the following general form:

$$
\begin{equation*}
\eta_{2}=\zeta+\sum_{i=1}^{m} \sigma_{i}\left(\lambda_{1} c_{i}+\lambda_{2} a_{i}\right)+\sum_{i=1}^{l} \frac{\partial \varphi}{\partial \alpha_{i}} e_{i}+\sum_{s=m+1}^{n} \psi_{s} f_{s} \tag{3,8}
\end{equation*}
$$

Here $e_{1}, \ldots, e_{l}, f_{m+1}, \ldots, f_{n}$ are constants and the component $\zeta$ is a particular solution of (3.4), which by virtue of (3.7) is $T$-periodic in $t$ and satisfies relations (3.6).

After an appropriate integration of these relations we obtain

$$
z_{r} \xi=\sum_{i=1}^{m} z_{r} \frac{\partial x_{1}}{\partial x_{i}} a_{i}- \begin{cases}\lambda_{1}{ }^{2} a_{r} t & (r=1, \ldots, m)  \tag{3.9}\\ \lambda_{1} c_{r} t & (r=m+1, \ldots, l) \\ \lambda_{1} d_{r-l+m} & (r=l+1, \ldots, l+n-m)\end{cases}
$$

The system of equations for determining the periodic third approximation $\eta_{3}$ is

$$
\begin{align*}
\eta_{3} \cdot & =\left(\frac{\partial X}{\partial x}\right) \eta_{3}+\left[\left(\frac{\partial^{\prime}}{\partial \mu} \frac{\partial X}{\partial x}\right)-\lambda_{2} E_{k}\right]\left[\lambda_{1} \sum_{i=1}^{m} \sigma_{i} a_{i}+\sum_{i=1}^{i} \frac{\partial \varphi}{\partial \alpha_{i}} c_{i}+\right.  \tag{3.10}\\
& \left.\sum_{s=m+1}^{n} \vartheta_{s} d_{s}\right]-\lambda_{3} \sum_{i=1}^{m} \frac{\partial \varphi}{\partial x_{i}} a_{i}-\lambda_{1}\left[\zeta+\sum_{i=1}^{m} \sigma_{i}\left(\lambda_{1} c_{i}+\lambda_{2} a_{i}\right)+\right. \\
& \left.\sum_{i=1}^{l} \frac{\partial \varphi}{\partial x_{i}} e_{i}+\sum_{s=m+1}^{n} \vartheta_{s} f_{s}\right] .
\end{align*}
$$

The conditions for the $T$-periodicity of $\eta_{3}$ are determined by the usual methods. Here, however, besides relations (1.14), (1.16), (2.6), (2.8)-(2.10) and (3.5) we should alsokeep (1.11) and (3.9) in mind, By virtue of these latter relations we have, with due regard to (3.7),

$$
\begin{align*}
& \int_{0}^{T} z_{r}\left(\frac{\partial^{\prime}}{\partial \mu} \frac{\partial X}{\partial x}\right) \sigma_{i} d t=\sum_{s=1}^{m} \chi_{s i} \frac{\partial P_{r}}{\partial h_{s}}, \quad \int_{0}^{T} z_{r} \zeta d t=\sum_{i=1}^{m} p_{r i} u_{i}  \tag{3.11}\\
& p_{r i}=\int_{0}^{T}\left(z_{r} \frac{\partial x_{1}}{\partial x_{i}}-\frac{\partial P_{r}}{\partial x_{i}} \frac{t}{T}\right) d t
\end{align*}
$$

Finally we arrive at the following system of $l+n-m$ linear inhomogeneous equations for determining the unknowns $c_{1}, \ldots, c_{m}, e_{m+1}, \ldots, e_{l}, f_{m+1}, \ldots, f_{n}$ :

$$
\begin{align*}
& \sum_{i=1}^{l} \frac{\partial P_{r}}{\partial \alpha_{i}} c_{i}+\sum_{s=m+1}^{n} \frac{\partial^{*} P_{r}}{\partial h_{s}} d_{s}+\lambda_{1} \sum_{i, s=1}^{m} \chi_{s i} \frac{\partial P_{r}}{\partial h_{s}} a_{i}=  \tag{3.12}\\
& \quad \lambda_{1} \sum_{i=1}^{m} p_{r i} a_{i}+T \times \begin{cases}2 \lambda_{1} \lambda_{2} a_{r}+\lambda_{1} c_{r} & (r=1, \ldots, m) \\
\lambda_{2} c_{r}+\lambda_{1} e_{r} & (r=m+1, \ldots, l) \\
\lambda_{2} d_{r-l+m}+\lambda_{1} f_{r-l+m} & (r=l+1, \ldots, l+n-m)\end{cases}
\end{align*}
$$

The construction carried out permits us to determine the first two approximations $\lambda_{1}$ and $\lambda_{2}$ to the nonsimple critical indices of the mode. Naturally, from system (3.7), the subsystem of the first $m$ equations in the unknowns $a_{1}, \ldots, a_{m}$ arises. The condition that the latter's determinant equals zero yields the equation

$$
\begin{equation*}
\left|\frac{\partial P_{r}}{\partial \alpha_{i}}-\delta_{i r} \lambda_{1}^{2} T\right|_{i, r=1, \ldots, m}=0 \tag{3.13}
\end{equation*}
$$

allows us to find the $m$ values of the quantity $\lambda_{1}{ }^{2}$. In the case of stability all these values should be real and negative. We say that the corresponding $m$ inequalities $\left(\lambda_{1}{ }^{2}<0\right)$ constitute stability criteria of the second group for the periodic mode.

The fulfillment of the stability criteria of the second group ensures only that the first approximations to the nonsimple characteristic indices are imaginary ( $\operatorname{Re} \lambda_{1}=0$ ). Therefore, a complete judgment on the signs of the real parts of these indices is obtained from the expressions for the second approximations $\lambda_{2}$. The appropriate expressions are
easily obtained from the first $m$ equations in (3.12), which form the following linear inhomogeneous system for determining the constants $c_{1}, \ldots, c_{m}$

$$
\begin{align*}
& \sum_{i=1}^{m} \frac{\partial P_{r}}{\partial \alpha_{i}} c_{i}-\lambda_{1}^{2} T c_{r}=\lambda_{1}\left\{2 \lambda_{2} T a_{r}-\sum_{i=1}^{m}\left[\sum_{s=1}^{m} \chi_{s i} \frac{\partial P_{r}}{\partial h_{s}}+\right.\right.  \tag{3.14}\\
& \left.\left.\frac{1}{\lambda_{1}^{2} T}\left(\sum_{s=m+1}^{l} \frac{\partial P_{r}}{\partial \alpha_{s}} \frac{\partial P_{s}}{\partial \alpha_{i}}+\sum_{s=m+1}^{n} \frac{\partial^{*} P_{r}}{\partial h_{s}} \frac{\partial P_{s+l-m}}{\partial \alpha_{i}}\right)-p_{r i}\right] a_{i}\right\}
\end{align*}
$$

In the derivation of system (3.14) the magnitudes of the constants $c_{m+1}, \ldots, c_{l}, d_{m+1}, \ldots$ $d_{n}$ were eliminated by means of (3.7). The determinant of the homogeneous part of system (3.14) coincides with (3.13) and, consequently, vanishes. Therefore, to be able to solve this system we should impose specific constraints on its right-hand sides. The corresponding relations, in a form solved with respect to $\lambda_{2}$ are

$$
\begin{gather*}
\lambda_{2}=\frac{1}{2 T \sum_{r=1}^{m} a_{r} a_{r}^{*}} \sum_{i, r=1}^{m}\left[\sum_{s=1}^{m} \chi_{s i} \frac{\partial r_{r}}{\partial h_{s}}+\frac{1}{\lambda_{1} 2 T}\left(\sum_{s=m+1}^{l} \frac{\partial P_{r}}{\partial \alpha_{s}} \frac{\partial P_{s}}{\partial \alpha_{i}}+\right.\right.  \tag{3.15}\\
\left.\sum_{s=m+1}^{n} \frac{\partial^{*} P_{r}}{\partial h_{s}} \frac{\partial P_{s+l-m}}{\partial \alpha_{i}}\right)-p_{r i} \mid a_{i} a_{r}^{*}
\end{gather*}
$$

Here the numbers $a_{1}{ }^{*}, \ldots, a_{m}{ }^{*}$ form the solution of the system

$$
\begin{equation*}
\sum_{r=1}^{m} \frac{\partial P_{r}}{\partial x_{i}} a_{r}^{*}=\lambda_{1}{ }^{2} T a_{i}^{*} \quad(i=1, \ldots, m) \tag{3.16}
\end{equation*}
$$

conjugate to the first group of Eqs. (3.7).
If all $m$ roots $\lambda_{1}{ }^{2}$ of Eq. (3.13) are nonzero and have simple elementary divisors (we shall assume this), then to each such root there corresponds its own set of numbers $a_{1}, \ldots, a_{m}, a_{1}{ }^{*}, \ldots, a_{m}{ }^{*}$ and its own magnitude of $\lambda_{2}$ computed by formula (3.15). Thus, the nonsimple characteristic indices of the mode separate in a natural fashion into $m$ pairs of the form

$$
\begin{equation*}
\lambda_{r}^{(1,2)}= \pm \lambda_{1}^{(r)} \mu^{1 / 2}+\lambda_{2}^{(r)} \mu \pm \mu^{3 / 2} \ldots \quad(r=1, \ldots, m) \tag{3.17}
\end{equation*}
$$

If the stability criteria of the second group are fulfilled, then all the numbers $\lambda_{2}$ are real, and for a definitive judgment on stability we should verify the fulfillment of the $m$ inequalities $\lambda_{2}^{(r)}<0$. We call this group of inequalities the stability criteria of the third group.

In conclusion we note that the relations obtained in this paper permit us to predetermine the existence and the stability of the mode in the autonomous case as well, To do this, however, the generating system should be chosen so that the frequency of its periodic solution equals unknown frequency $v$ of the desired mode. Furthermore, the quantity $v$ in Eqs. (1.5), (1.17) should be replaced by the first approximation $v_{0}$ to it. Then in the autonomous case the quantities $v_{0}, \alpha_{2}-\alpha_{1}, \ldots, \alpha_{l}-\alpha_{1}, h_{1}, \ldots, h_{n}$ are uniquely determined from these equations. It is also essential here that the determinant of system (2.13) have a zero root, and the total number of stability criteria of the first group is lessened by unity. We can convince ourselves of the latter by summing the first $l$ columns of the determinant of system (2.13) with due regard to the fact that

$$
\partial P_{r} / \partial \alpha_{1}+\ldots+\partial P_{r} / \partial \alpha_{l}=0
$$

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# FORCED OSCILLATIONS WITH A SLIDING REGIME RANGE OF A TWO-MASS SYSTEM INTERACTING WITH A FIXED STOP 

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We investigate, by the method developed in [1], the forced oscillations with a sliding regime range of a two-mass system with elastic connection between the elements, impacting a fixed stop. The system being considered is a dynamic model for a number of vibrational mechanisms. Forced oscillations with a sliding regime range of a system with shock interactions are periodic motions accompanied by a period of an infinite succession of instantaneous collisions of two fixed elements of the model [2]. Within the framework of conditions of roughness of the parameter space [3], in this paper we study by the method of [1] periodic motions with a sliding regime range of a two-mass system with a stop. This problem was posed because in real systems the velocity recovery factor $R$ changes from shock to shock, mainly taking small values ( $0,0.2$ ). At the same time, the regions of realizability of one-impact oscillations, in practice the most essential ones among motions with a finite number of interactions over a period, narrow down sharply as $R$ decreases and becomes very small even for $R<0.6$ [4]. Thus, the stability of the given operation can be ensured by a law of motion which is independent or weakly dependent on $R$ (*) (see footnote on the next page). By virtue of what has been said above,

